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SOLVE.®

# PlantPAx MPC Introduction

## Powerful Embedded Model Predictive Control



Allen-Bradley • Rockwell Software

**Rockwell**  
**Automation**

# MPC Drives Performance

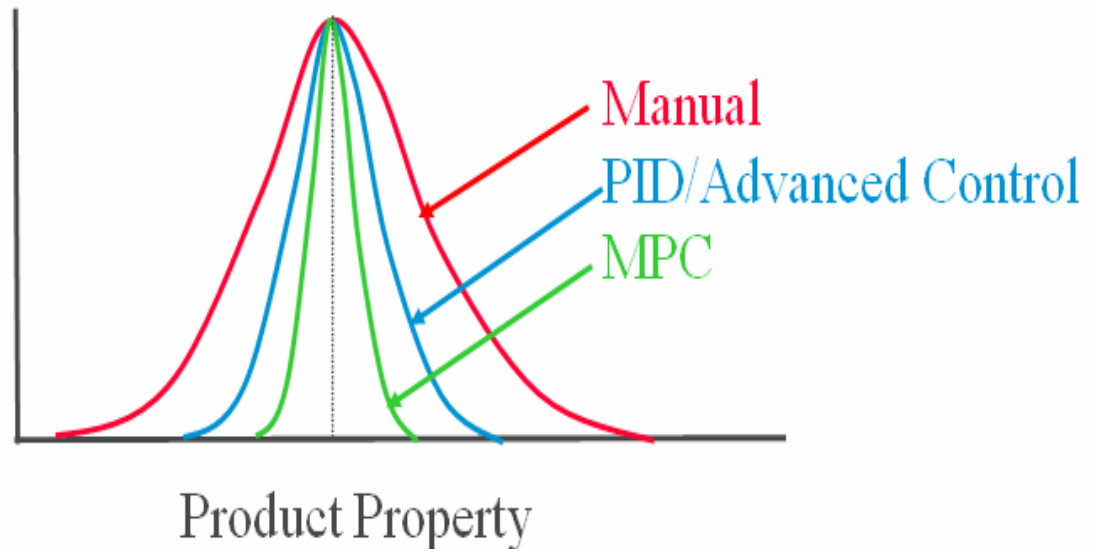
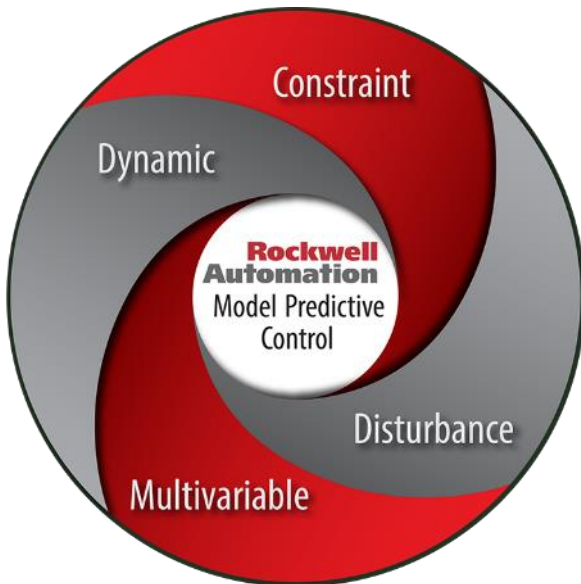
What would it mean to your business if you could:

- Increase Production
- Reduce Scrap
- Run Closer to Product Quality Targets and Limits
- Reduce Energy per Pound of Product
- Reduce Environmental Impact



# MPC versus PID Control

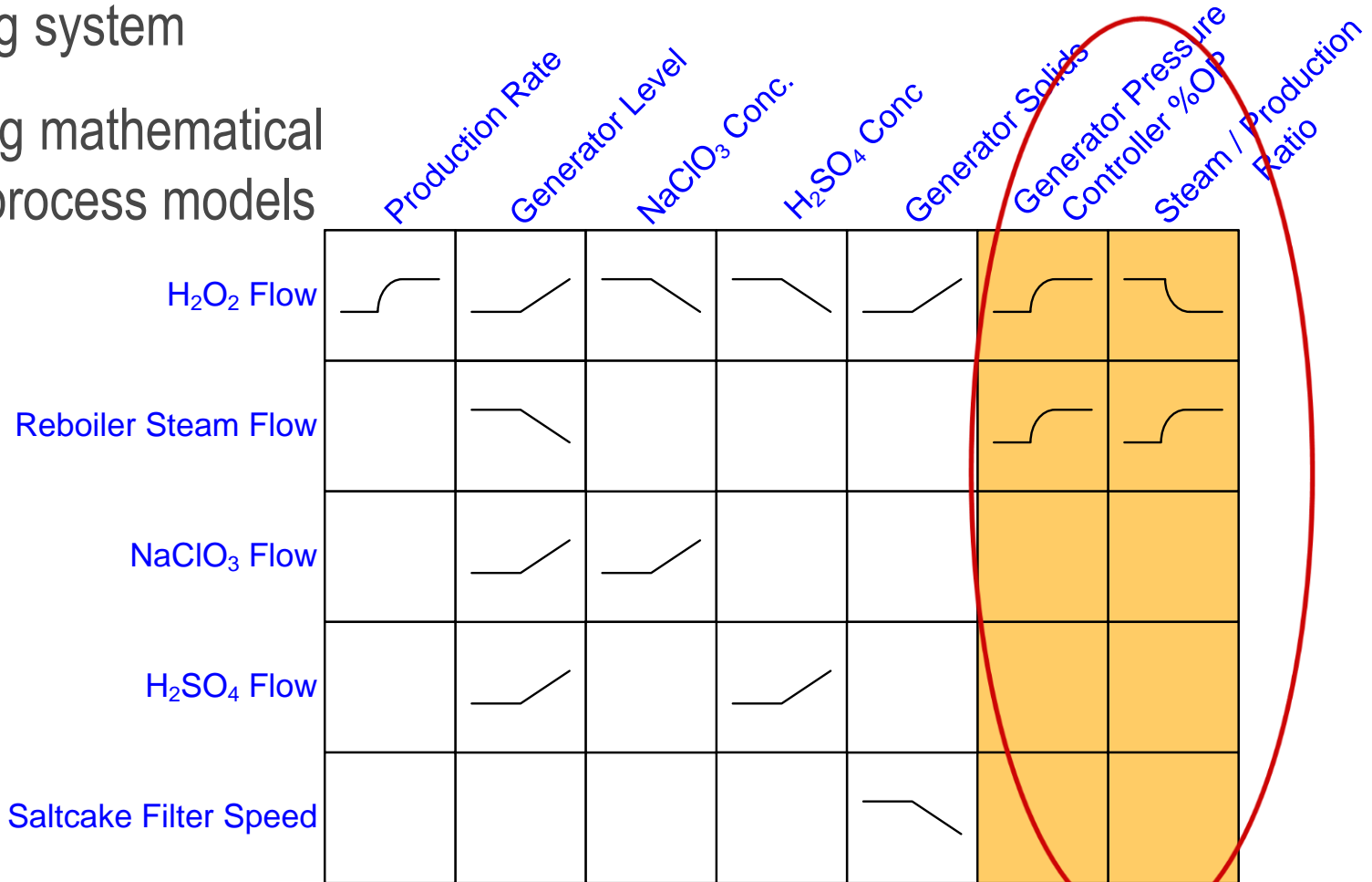
- Coordinate multiple interacting PIDs
- Predictably manage external disturbances
- Handle long or complex process dynamics
- Maximize performance up to process limits
- PID tuning is subjective and requires time and experience



# ClO<sub>2</sub> Generation Example

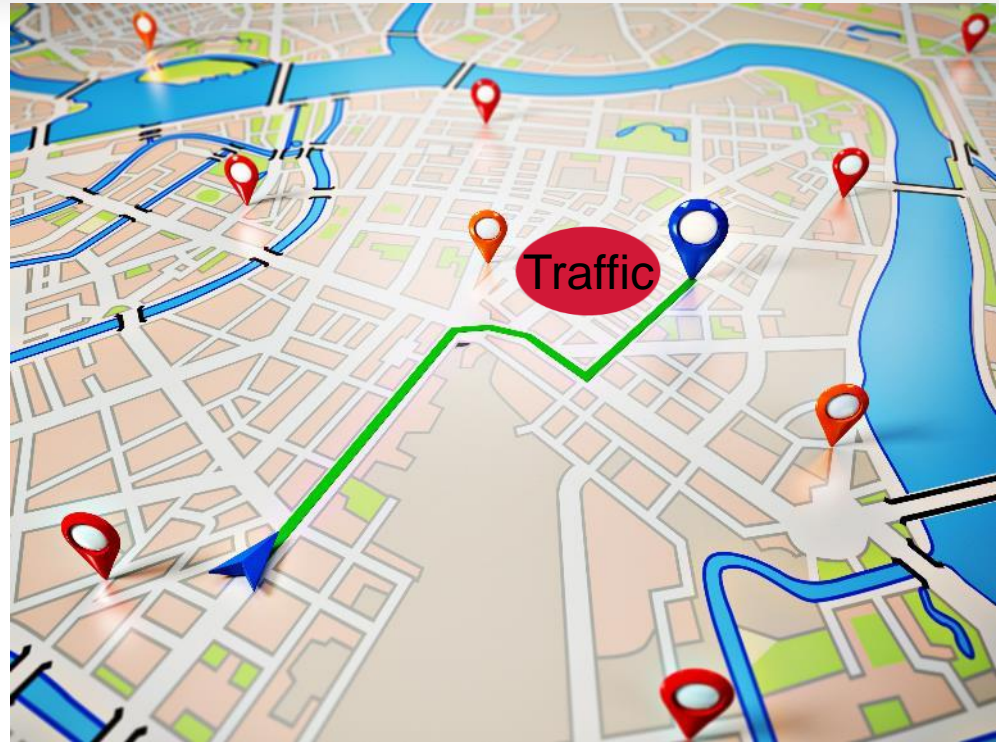
- Control of an unstable processing system
- Leveraging mathematical dynamic process models

Constraints



# PlantPAX has the only embedded MPC

- That senses and reroutes your control when a bottleneck happens
- That allows closed-loop adjustment of all tuning & model parameters
- That leverages trajectory information fully on cascade controllers, on sequential controllers and on known disturbance paths.
  - That supports up to 10 MVs, 10 CVs & 10 DVs



- And is fully embedded in PlantPAX: runs in controllers, complete faceplate integration, uses RA programming standards.

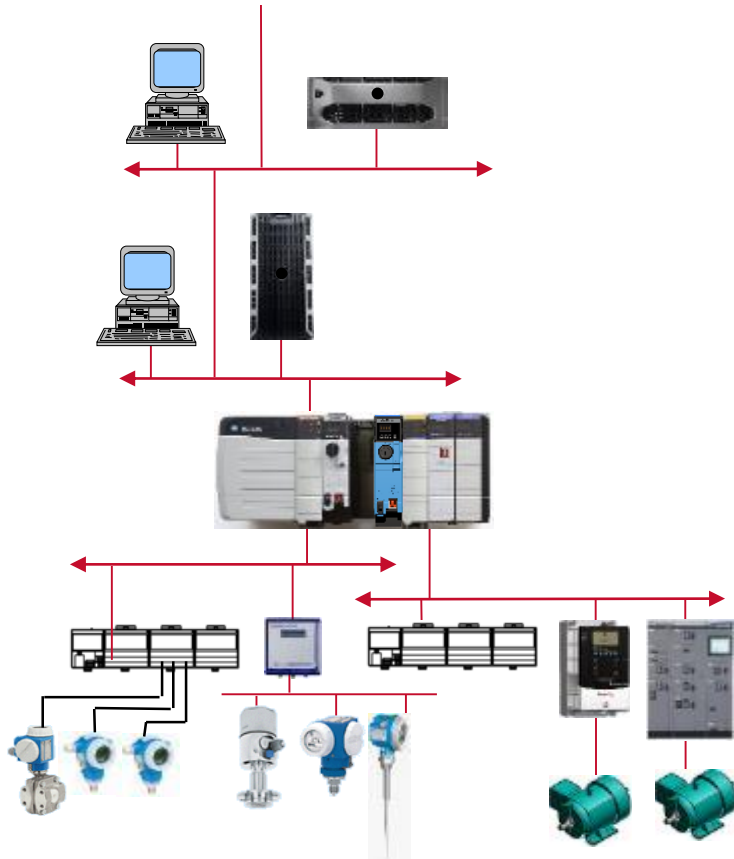
# PlantPax APC in Integrated Architecture

## Workstation and Logix-based APC Products

FactoryTalk® ProductionCentre, FactoryTalk® Historian,  
**Pavilion® Real-Time Optimization™** ...

**Pavilion8® MPC, Software CEM®, VOA®,** Asset Management, ...

Rockwell Software Studio 5000®, **PlantPax™ MPCBuilder,**  
**PlantPax™ ModelBuilder**



- **PlantPax® MPC**
- **IMC,CC,MMC**
- **FuzzyLogic**
- **SoftSensor® (AOI)**
- **PID,PIDE**
- Motion
- Discrete

# Traditional MPC Limitations

- One Control Platform
  - A Controller is a more reliable/robust platform (reduced maintenance)
  - A Controller is designed to easily integrate calculations and measurements (eases deployment)
  
- One Platform to Maintain
  - Some users are more comfortable with integration of measurements, outputs and MPC on a single platform.
  - One user interface is used for integrating MPC, support calculations and adding/configuring measurement integration.
  
- That acts faster
  - Online optimization has been slow and expensive
  - Execution cycles have been in minutes, not sub-second

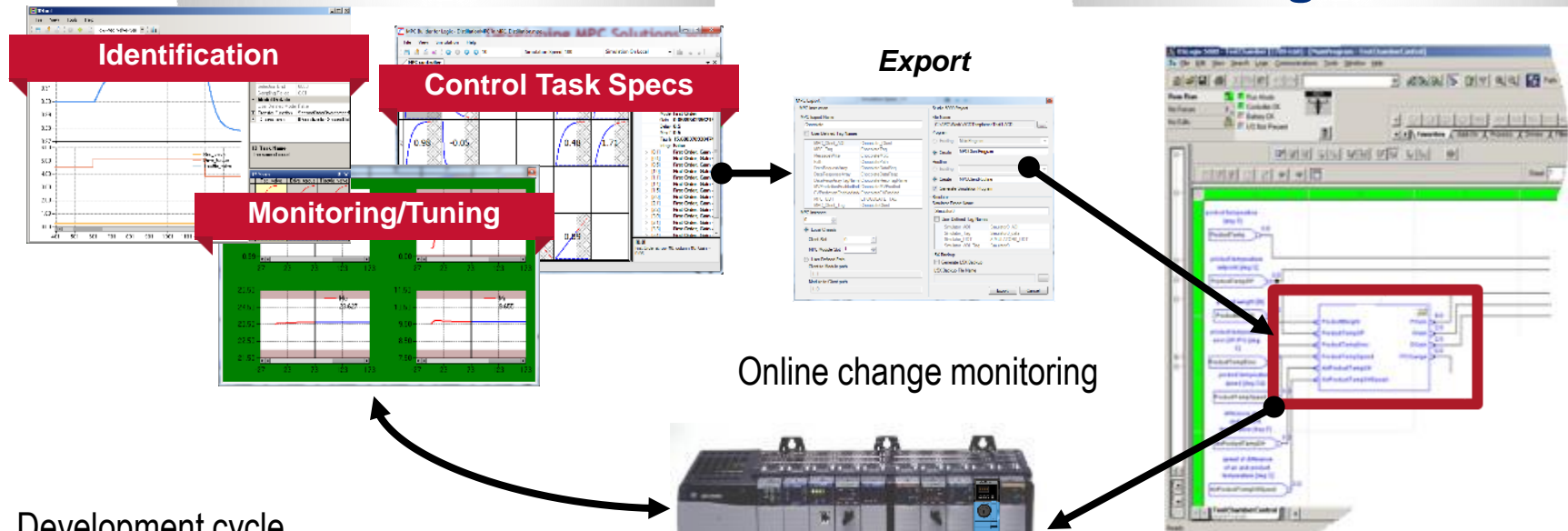
# PlantPAx MPC Capabilities

- **Develop and implement MPC up to 10 CV's, 10 MV's and 10 DV's**
  - Calculation optimization up to 9 control moves (default 6)
  - Predictive horizon up to 200 controller steps (frequency is a user specification)
  
- **Execute up to five independent MPC applications on one MPC-module**
  
- **Fully functional MPC**
  - Incorporates a solver and dynamic constraint management
  - Allows on-the-fly model and tuning parameter adjustment
    - In open or closed-loop
    - Will slow calculation speed, so grade-based model scheduling, not every execution is recommended or anticipated.
  - Allows trajectory passing including most relevant parameters (targets, disturbances, constraints)

# PlantPax MPC – Solution Development

## MPC Builder

## Logix5000



### Development cycle

1. Identify Process Parameters
2. Specify Targeted measurements & Limits
3. Generate MPC Shell AOI
4. Import and instantiate AOI
5. Download project to Logix
6. Monitor and tune

### Logix5000 program download

Dedicated MPC-Module  
(Co-Processor)  
AOI on Controller



# Chocolate Tempering Machine Control Task Demonstration



**Rockwell  
Automation**

- **Maintain Quality:** proper chocolate crystallization is achieved when maintaining the chocolate temperature at  $SP \pm 0.5$  [°C] at the machine outlet
  - **Maximize Yield:** maximize production and minimize the amount of chocolate, which has to be recycled
- Chocolate Tempering Machine Simulator**

- **Manipulated Variables:**

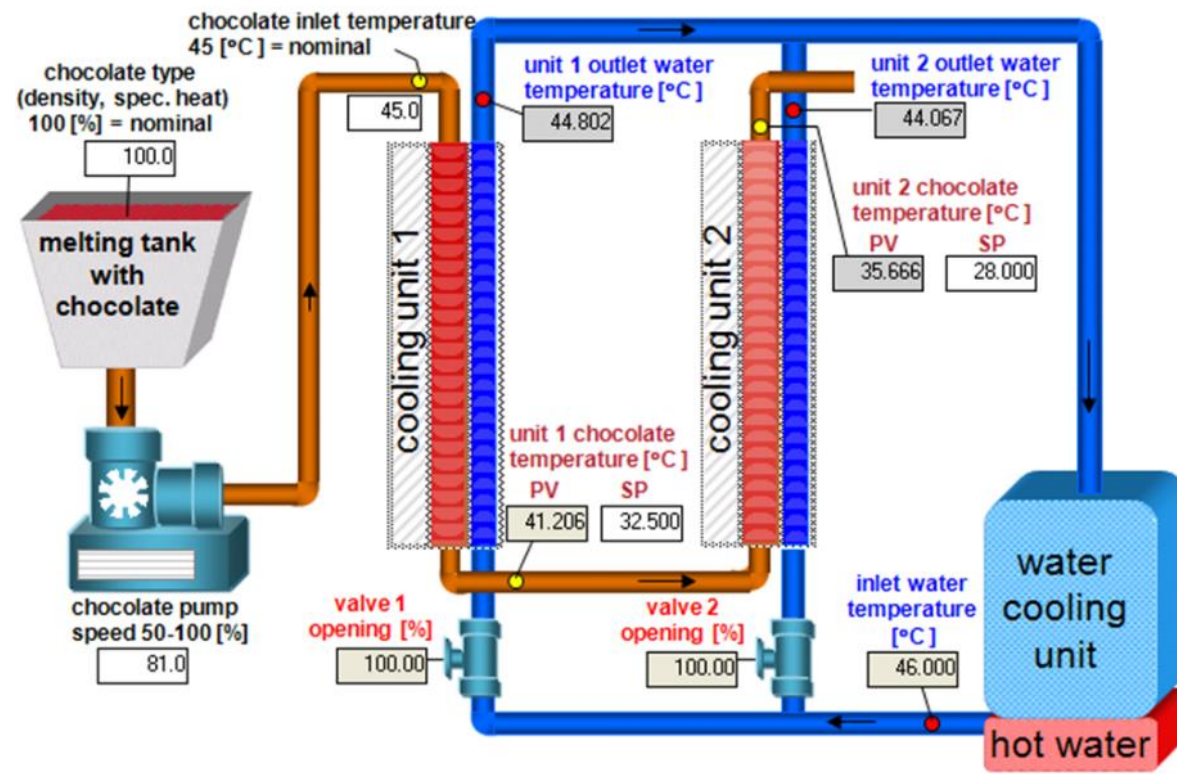
- unit 1 water valve opening [%]
- unit 2 water valve opening [%]
- chocolate feed rate [%]

- **Controlled Variables:**

- unit 1 outlet chocolate temperature [°C]
- unit 2 outlet chocolate temperature [°C]

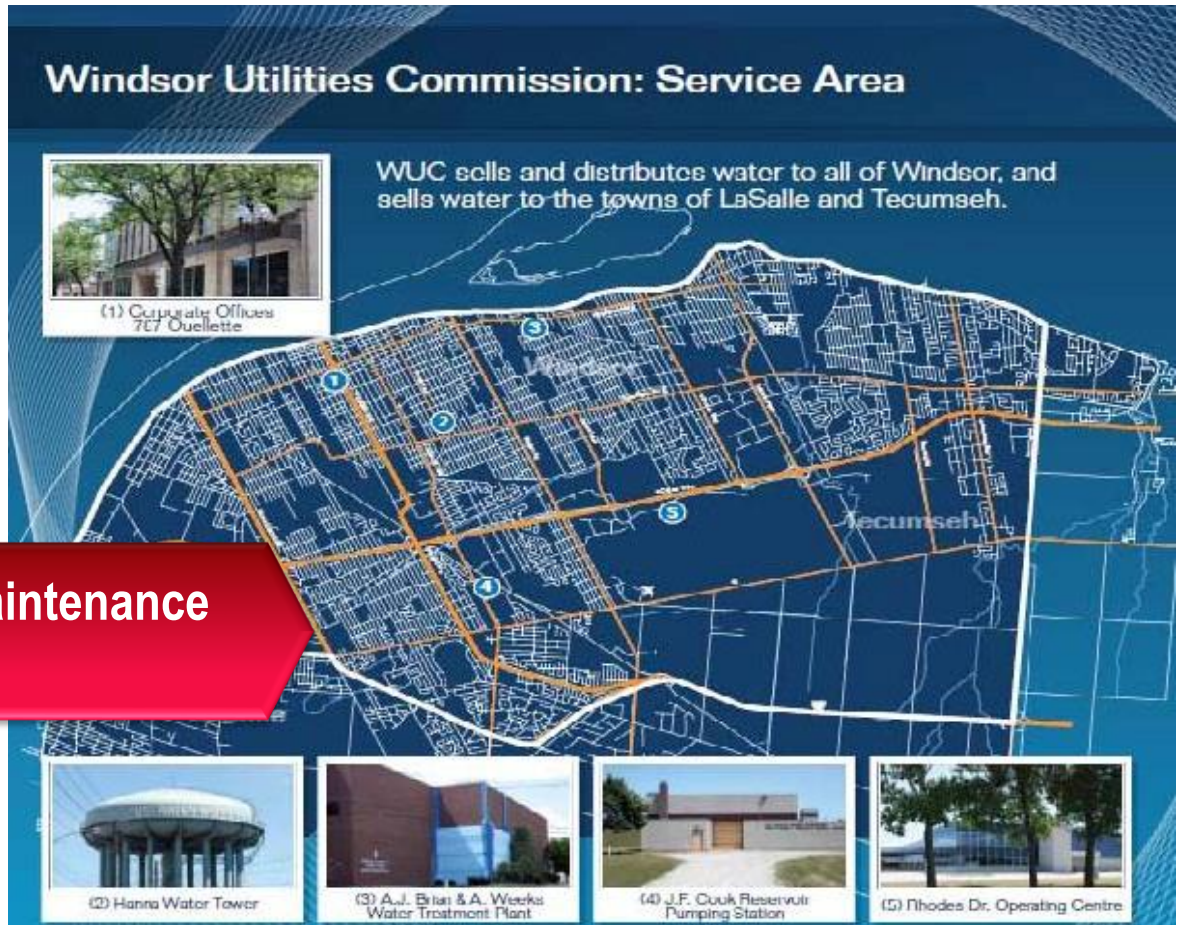
- **Disturbance Variables:**

- inlet water temperature [°C]
- type of chocolate [%]
- chocolate inlet temperature [°C]



# Installation 2: EnWin Water Pumping

- **Minimize Pressure:** Achieve minimum requirements at the end of many lines – but reduce leakage and pipe breaks.
- **Coordinate Pumps:** Respond to pumps turning on and off to meet varied demands.
- **Adapt Model:** to different pump



**21% reduced breaks and maintenance costs reported.**

# Custom APC Faceplate in FTView

P = Pressure Control    R = Running    O = Optimized  
M = Manual Control    S = Stopped    M = Manual

### Advanced Control & Optimization Overview

#### Minimum Pressures

Mode	Min	Actual
Downtown #10	60.7	64.0
Seminal #2	50.7	0.2
Lauzon #3	57.5	58.7
Rhodes #3	49.5	49.5
Mercer #5	49.5	52.0
University #12	52.0	56.0
Beals #13	51.0	55.0
Malden #15	55.0	60.0
Hanna	41.8	-2.1

Hannah Level    -2.1

Min: 60%    Max: 85%

#### AJ Brian Pumps

	Status	FCV	Mode	Opt
AJB#1		85%		
AJB#2		VSD 0%		
AJB#3				
AJB#4		0%		
GEO#1				
GEO#2				
GEO#3				

#### JF Cook Pumps

JFC#1		VSD		
JFC#2				
JFC#1				

#### Pressure Controllers

AJ Brian	Target	Actual	Speed
	65.0	64.8	84%

Idle

VFD%

Pump%

JF Cook	Target	Actual	Speed
	65.0	64.8	84%

Idle

VFD%

Pump%

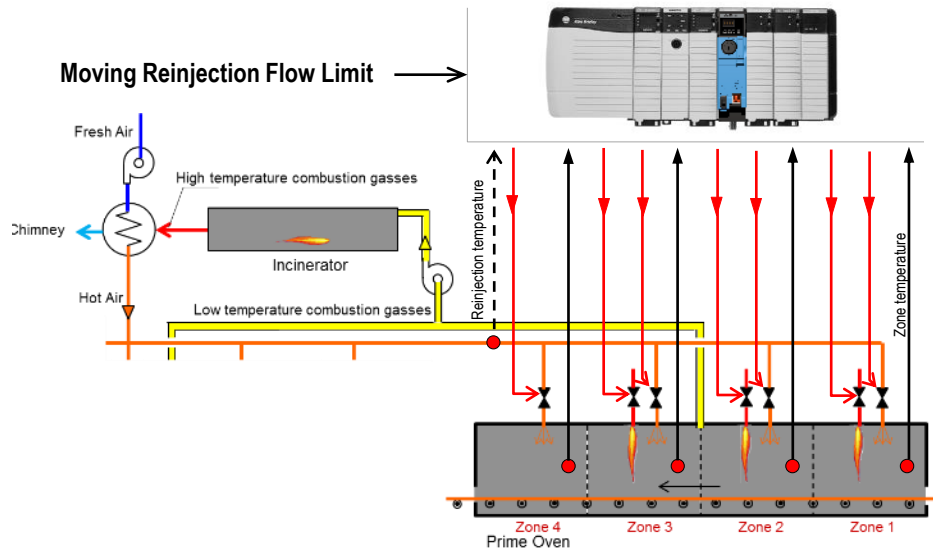
MPC Heartbeat

# Applied PlantPax MPC Coating Oven

## Classic Solution

## MPC Control

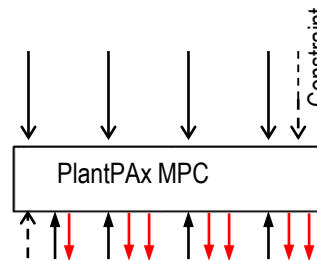
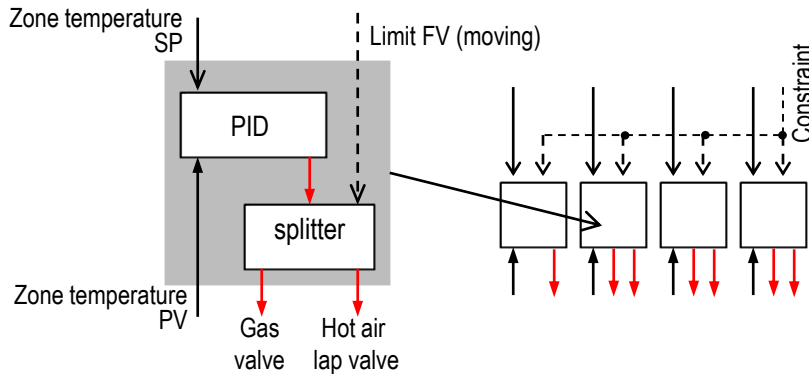
Organic Coating Oven



$$CV \times MV \times DV$$

$$4 \times 7 \times 2$$

↑       ↓       ↑



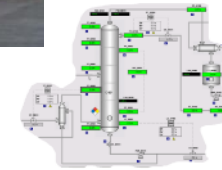
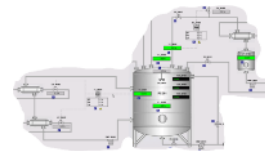
**Coordinate** heat recovery valves & gas

**Utilize** all waste heat

**Correct** for feed & incinerator changes

# Application Candidates PlantPAx MPC

- Distillation
- Evaporation
- Drying
- Boilers
- Milling
- Aeration Decks
- Centrifuge Balancing
- Stripping Columns
- Compressor
- Reactor
- And many more



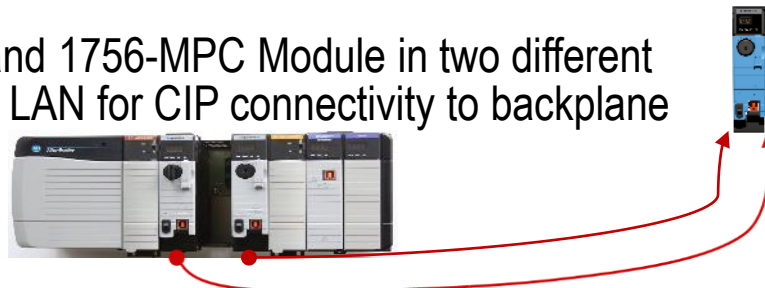


# Use case : acceptable configurations



Option 1 – Logix Controller and 1756-MPC Module in one chassis. Ethernet on control LAN for CIP connectivity to backplane (workstation monitoring).

Option 2 – Logix Controller and 1756-MPC Module in two different chassis. Ethernet on control LAN for CIP connectivity to backplane (workstation monitoring).

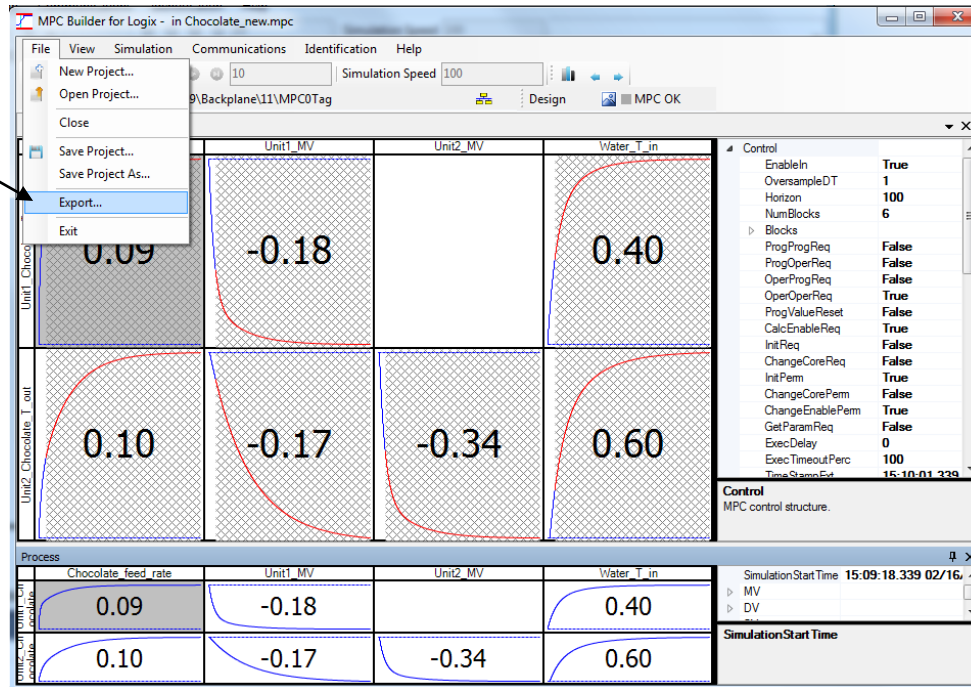


Option 3 – Logix Controller and multiple 1756-MPC Modules in one or more chassis.

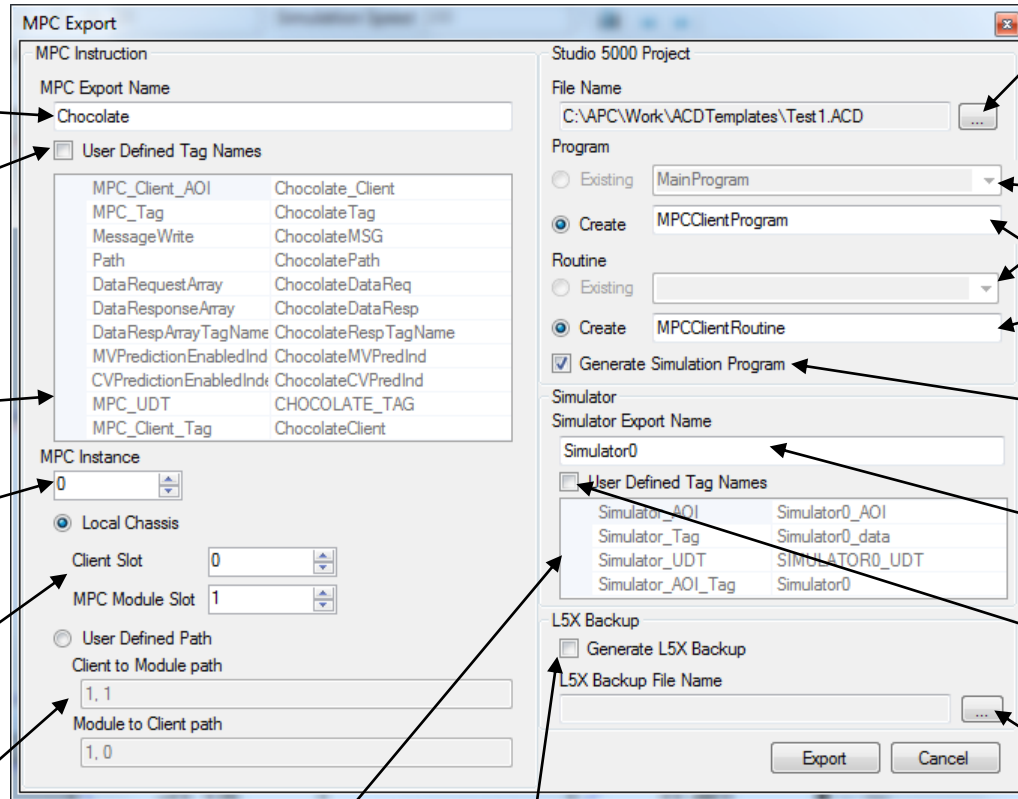


# Use case : Export & Configure AOI

If clicked,  
Export  
dialog is  
shown



# Use case : Export & Configure AOI



Export name used for generating default tag names

If selected, user defined tag names can be set

List of controller scope tags to be generated

MPC Module instance number (0 - 4)

Client Module & MPC Module slot numbers if both placed in one chassis

User defined CIP path if Client and MPC module are not in the same chassis

List of program scope simulator tags to be generated

If set, MPC is saved to L5X file for backup purposes or for online import

Selects .ACD file to which MPC will be added. ACD file cannot be opened in RSLogix.

List of existing Programs and Routines in the ACD file

New Program and Routine name if Create is set

If selected, process simulator with corresponding tags, AOIs and program is generated

Simulator export name used for generating default tag names

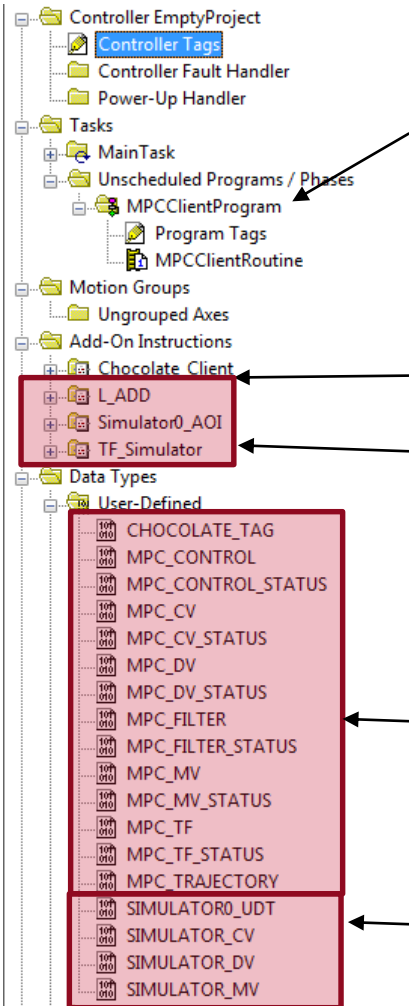
If selected, user defined simulator tag names can be set

Defines path to L5x backup file

# Use case : AOI in Studio5000

New program created during export. Placed to **Unscheduled Programs**. It must be placed to any fast periodic task (can't be placed in continuous task).

List of controller scope tags added to selected ACD project



**MPC AOI**  
**Simulator AOIs**

**MPC UDTs added**

**Simulator UDTs added**

Name	Alias For	Data Type
ChocolateClient		Chocolate_Client
ChocolateCVPredInd		INT
ChocolateDataReq		DINT[1006]
ChocolateDataResp		DINT[1006]
ChocolateMSG		MESSAGE
ChocolateMVPredInd		INT
ChocolatePath		STRING
ChocolateRespTagName		STRING
ChocolateTag		CHOCOLATE_TAG

# PlantPax MPC Faceplates

MVC0 MV Faceplate showing control parameters. The Setpoint Value is 90.00. The Setpoint Trajectory is a ramp from 0.0 to 90.0. The MV-SP is 0.00 and the MV is 1.00. The MV Target is 0.00. The Setpoint Trajectory is a ramp from 0.0 to 90.0. The MV-SP is 0.00 and the MV is 1.00. The MV Target is 0.00.

MV Faceplates

CV0 CV Faceplate showing a graph of Setpoint Value vs. PV. The Setpoint Value is 310.80 and the PV is 308.90. The Setpoint Value is 310.80 and the PV is 308.90. The Setpoint Value is 310.80 and the PV is 308.90.

CV Faceplates

PlantPax MPC Overview Faceplate showing a summary of controlled variables. It includes sections for Disturbance Variables, Manipulated Variables, and Controlled Variables. The status is 'Fault'.

MPC Overview Faceplate

Process Type and Display Limits Faceplate. It includes a table of process types with their parameters and a section for Display Limits.

Process Type	Equation	$T_1$	$T_2$	$\omega$	$\zeta$
Integrating	$K \frac{T_I s + 1}{T_I s + 1} e^{-T_D s}$	10.62	1.01	1.00	0.50
Non-Integrating	$K \frac{T_I s + 1}{\omega^2 s^2 + 2\zeta\omega s + 1} e^{-T_D s}$				

Display Limits: Minimum 0.00, Maximum 100.00

# PlantPax Better Process Control

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## Comments and Discussion

### PlantPax Model Predictive Control (embedded):

- Easy-to-use (graphical model-building, Studio5000 integration)
- Functional (full linear MPC, up to 10 by 10 matrix)
- Manages constraints, targets, trajectories and disturbances
- Model and control parameters adjustable on-line
- PlantPax HMI Standard Faceplates



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